

Traffic Incident Management System

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Introduction, Mission, and Need

- Why this System?
 - Personal experience in traffic.
- The TIMS will provide an incident management and resolution capability that quickly documents incidents, commands all stakeholders, clears the roadway, and directs passing traffic in order to reduce the impact traffic incidents have on society.
- Impacts
 - Reduce Travel Times (Commuters)
 - Improve Safety (Reduce Secondary Incidents)
 - Reduce Environmental Impact (Less fuel usage)
 - Reduce Costs (Transportation and Logistics Industry)

Requirements Development

- Stakeholders
 - Department of Transportation Personnel
 - Incident Responders
 - Transportation Industry Personnel
- Process
 - Identify user needs and CONOPs
 - Identify operational requirements
 - Derive performance requirements
 - Derive functional requirements
 - Derive constraint requirements



TRAFFIC INCIDENT MANAGEMENT HANDBOOK




U.S. Department of Transportation
Federal Highway Administration

Traffic Incident Management Handbook. Federal Highway Administration, 2010,
https://ops.fhwa.dot.gov/eto_tim_pse/publications/timhandbook/tim_handbook.pdf.

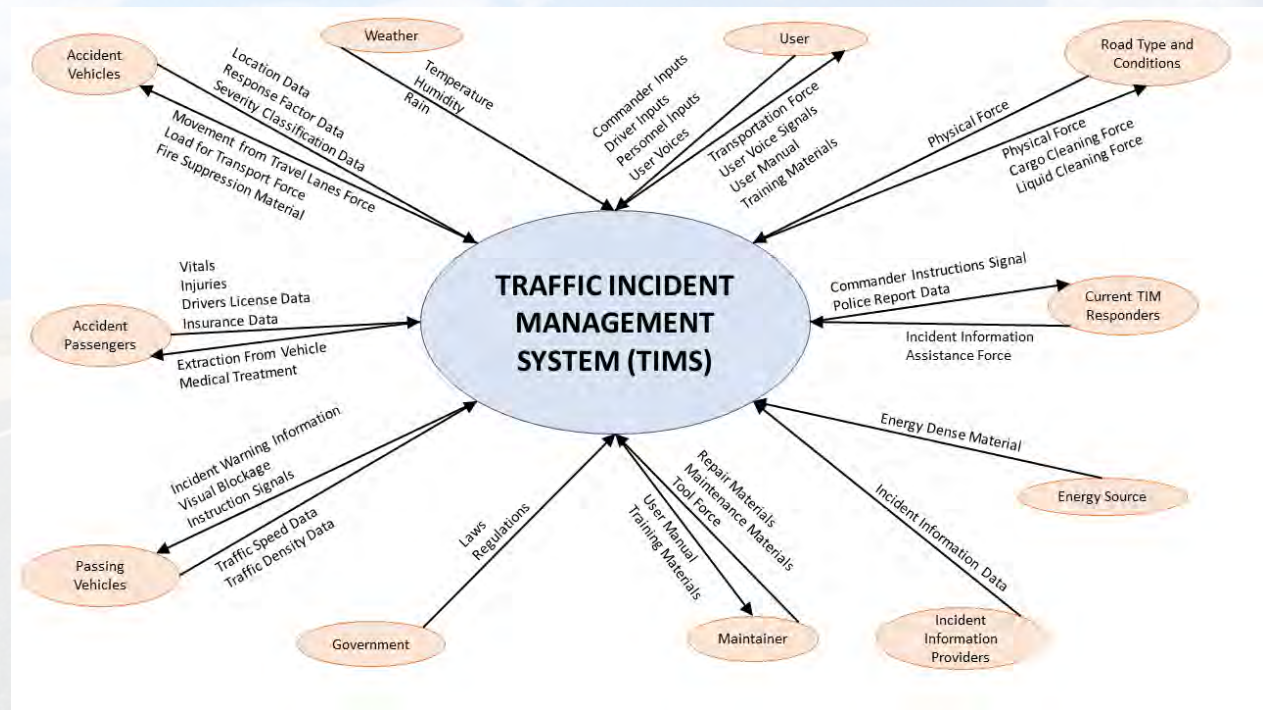
CONOPS

- Detect Incident
- Travel to Incident
- Plan Response
- Document the Scene
- Clear the Roadway

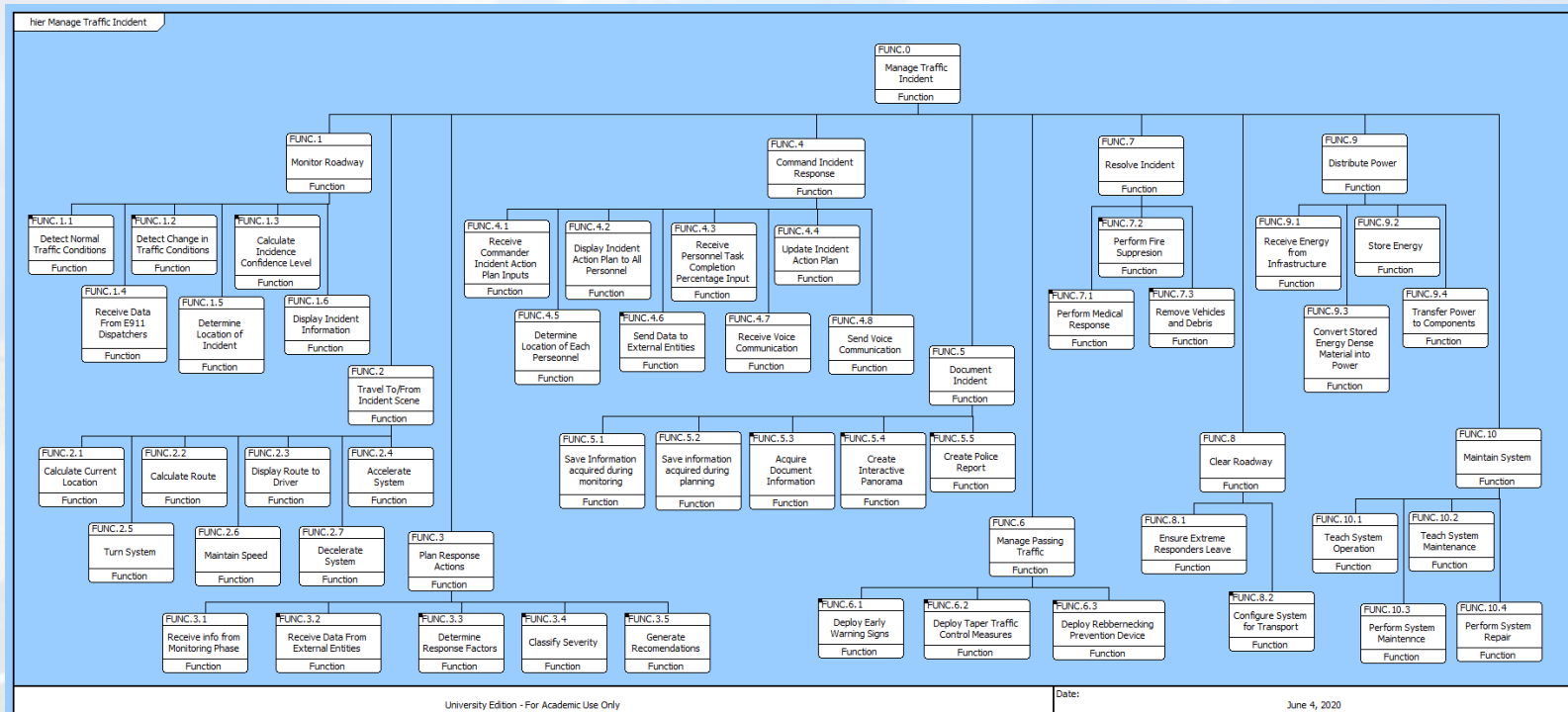


Functional Context Diagram

- Defines the interfaces between the system and external entities
- Shows what is passed between them.

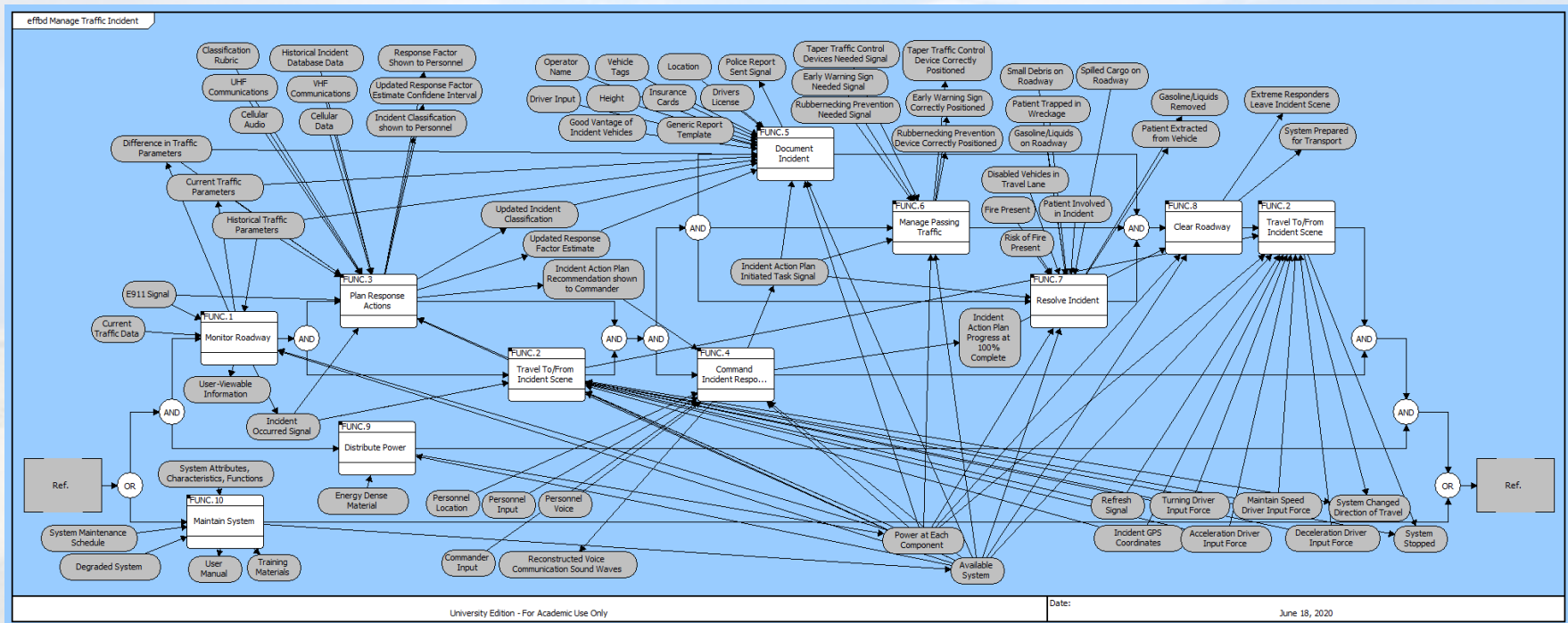


Functional Tree



- Shows the Level 1 and 2 functions.
- Level 3 and Level 4 functions decomposed for critical functions.

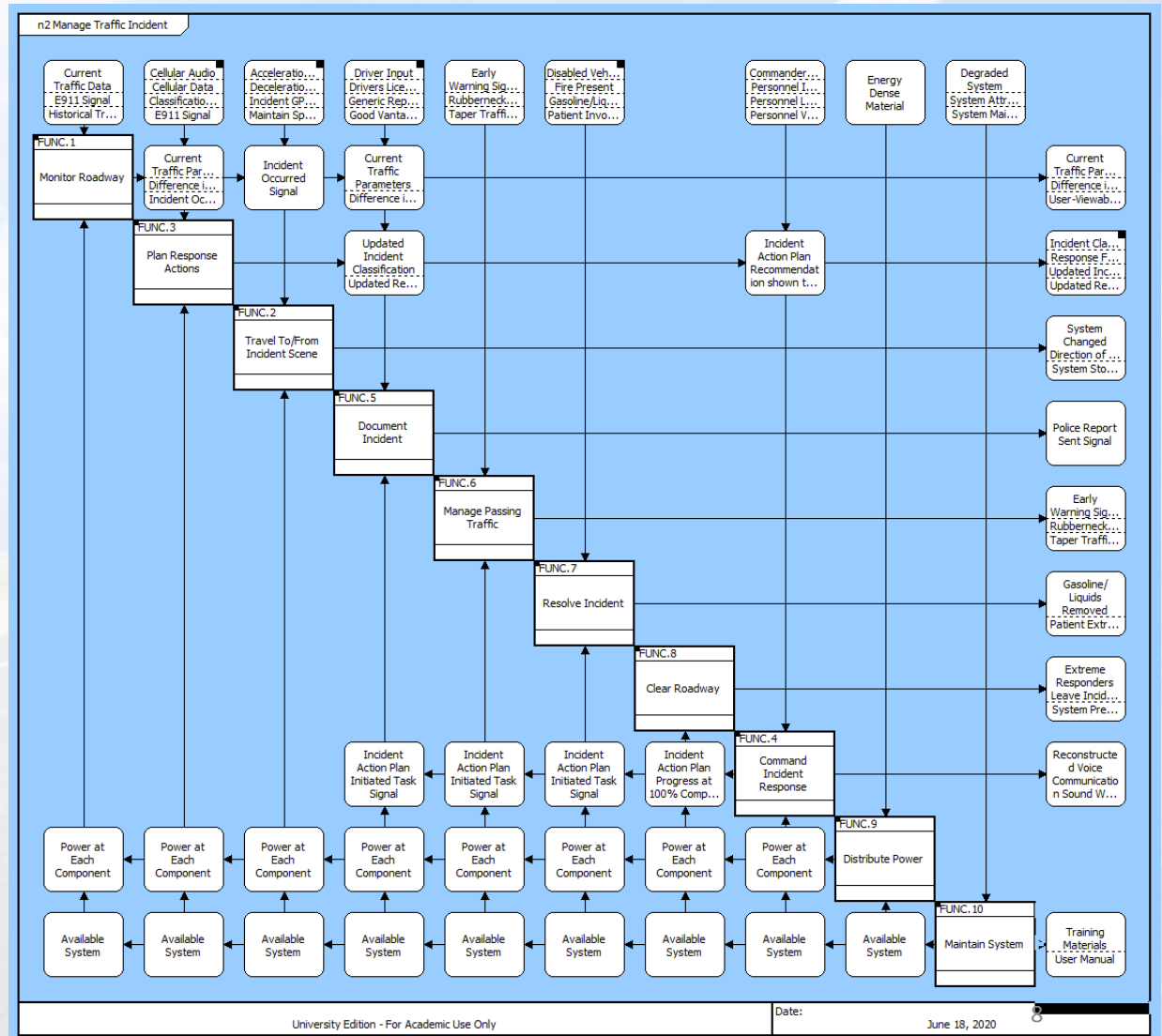
Enhanced Functional Flow Diagram



- Level 1 functions shown with logical operators.
- Inputs and outputs trace through the logical operators.

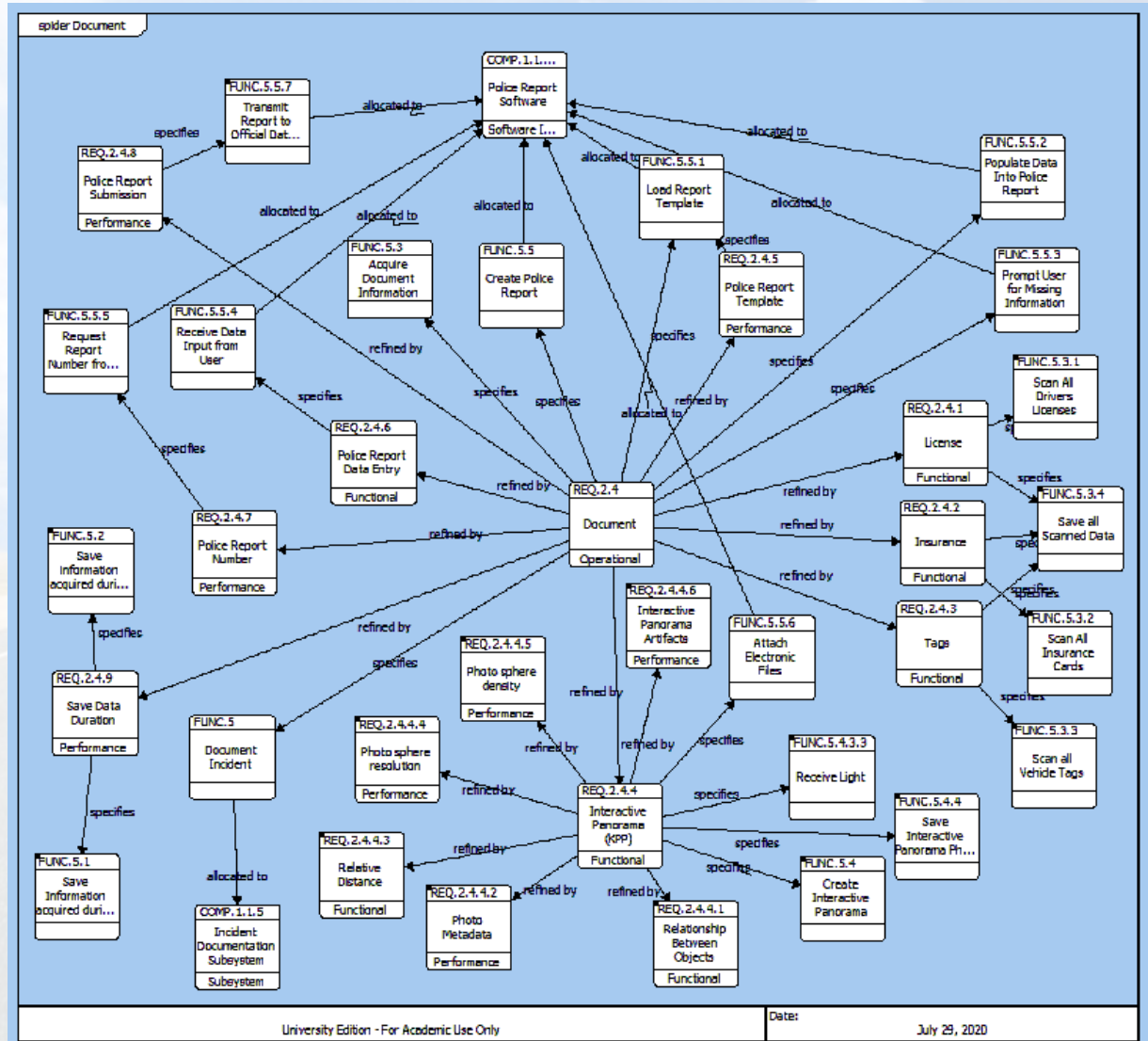
Functional N2 Diagram

- Functions listed along the diagonal.
- FEDS-M elements shown as inputs and outputs.
- External elements located in top row and right column.



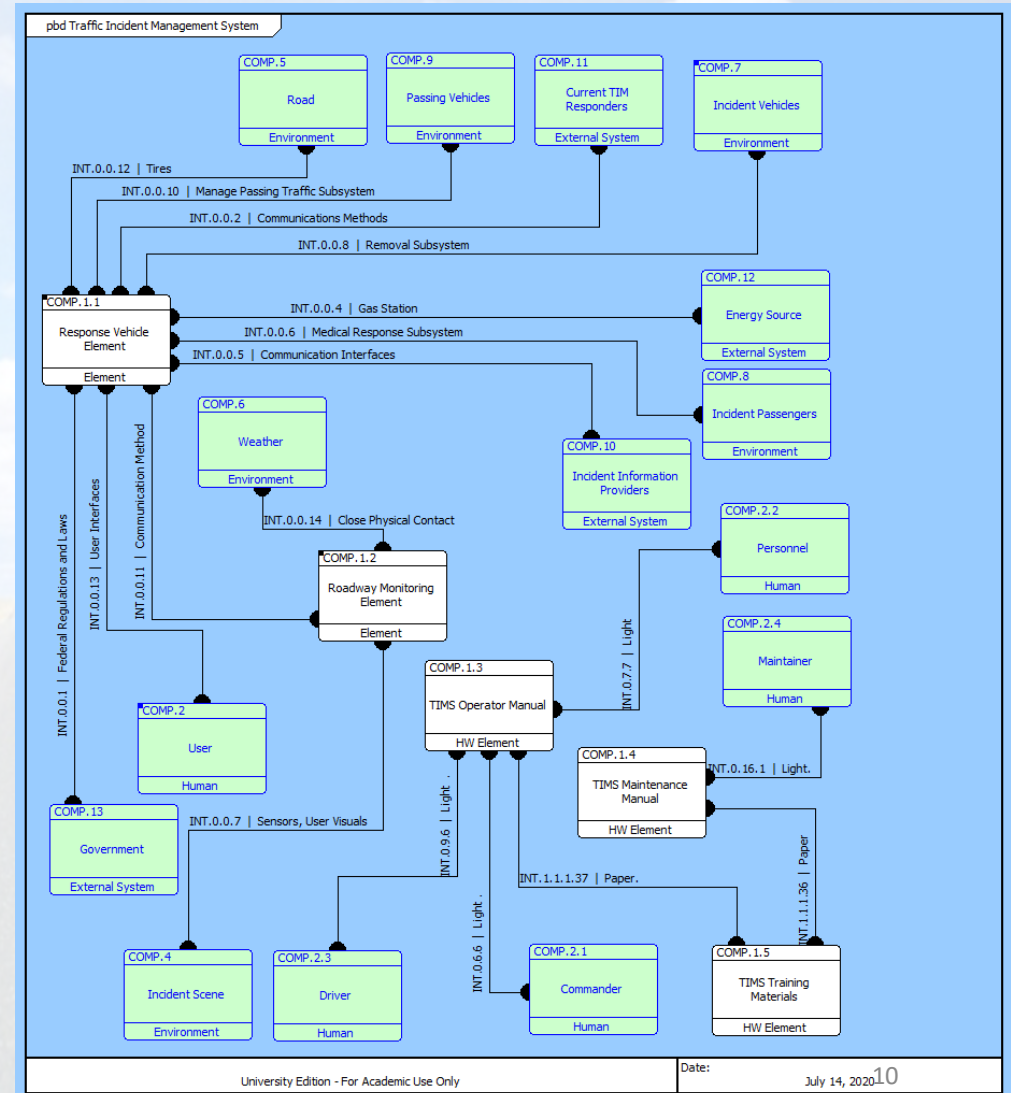
Traceability

- Most useful form is in a matrix.
- Establishes relationships.
- Determines completeness and over/under allocation.
- REQ.2.4
 - Refined by sub-REQs
 - Specifies FUNCs
 - Allocated to COMPs



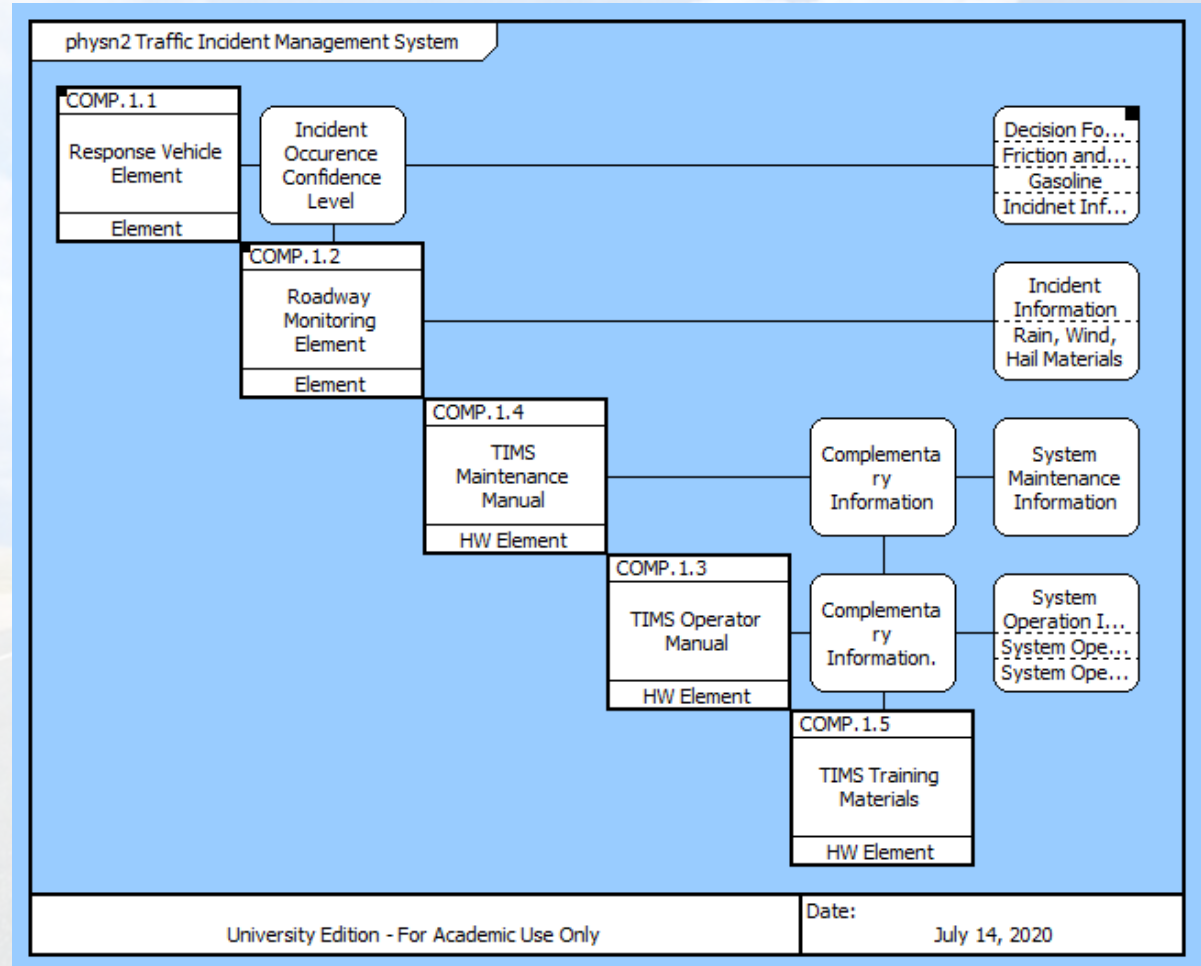
Physical Block Diagram – Level 1

- COMP.1 TIMS
- Shows implementation of external interfaces between components and external entities.
- Organizes internal components.



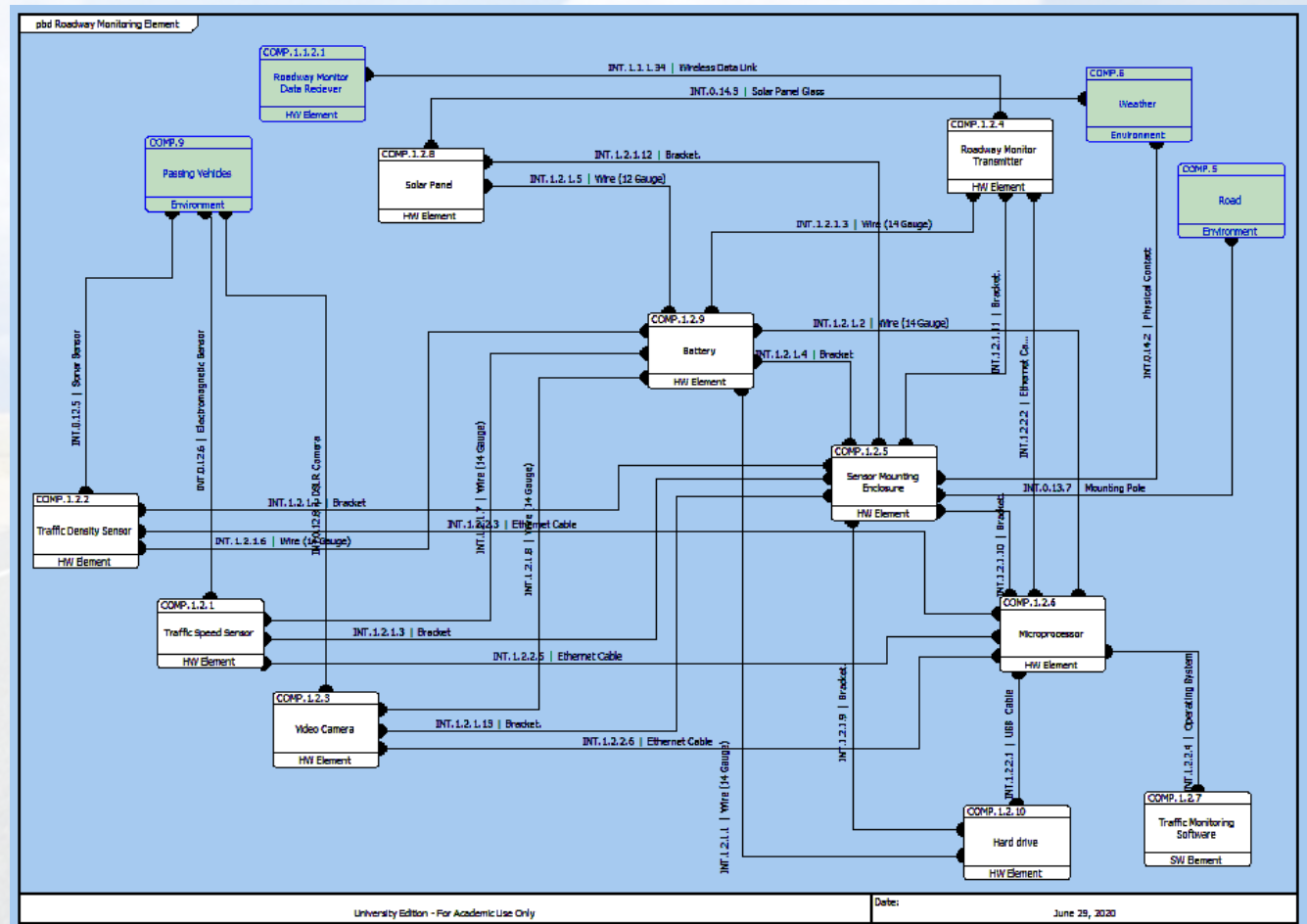
Physical N2 Diagram - Level 1

- COMP.1 TIMS
- Shows what is passed over each interface.
- Interfaces are not directional (all are located above/right of the diagonal.)



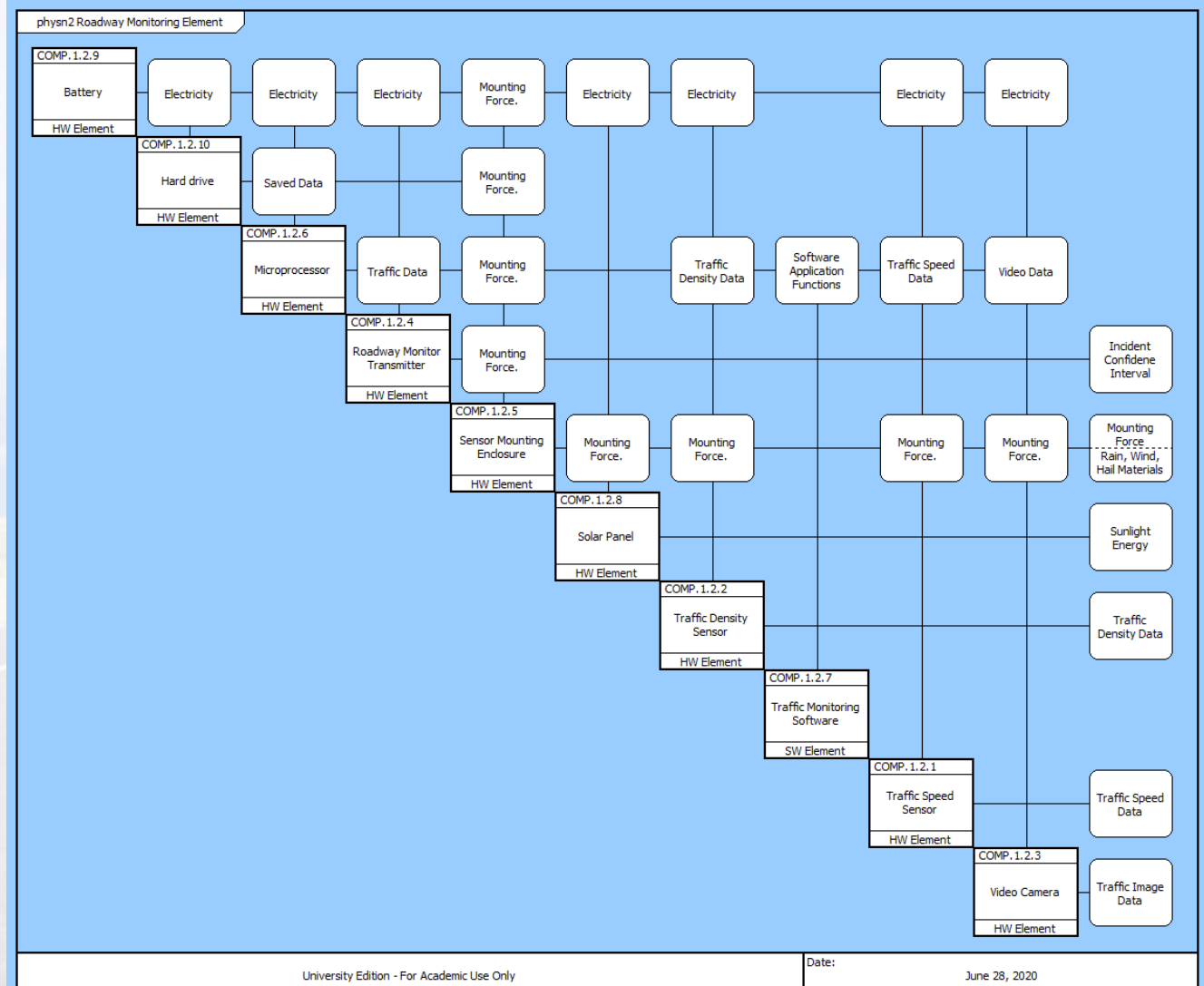
Physical Block Diagram – Level 2

- COMP.1.2 Roadway Monitoring Element
- Components and interfaces trace back to functions.
- Implementation of each interface is shown.



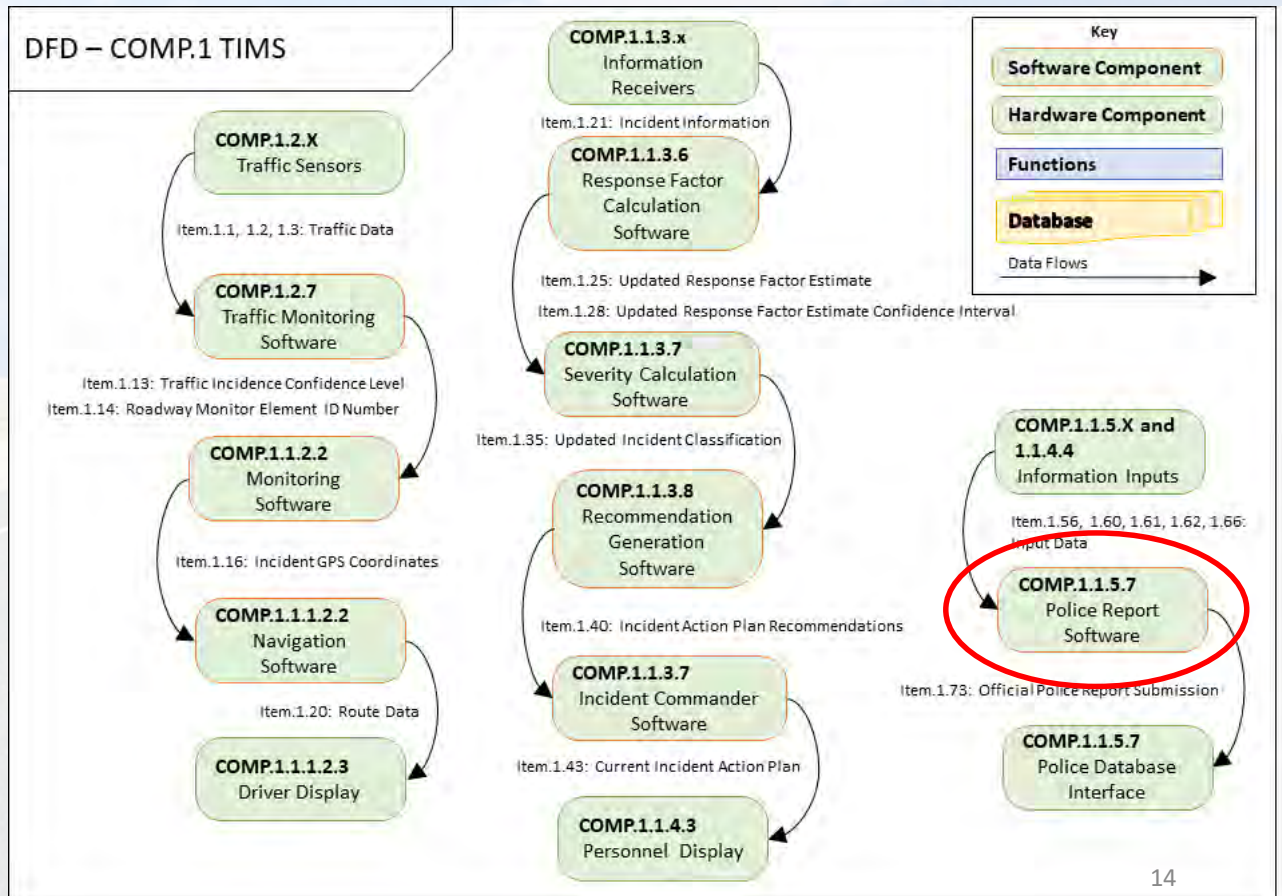
Physical N2 Diagram - Level 2

- COMP.1.2 Roadway Monitoring Element
- Shows what is passed over each interface.
- Interfaces are not directional (all are located above/right of the diagonal.)



Data Flow Diagram

- **COMP.1 TIMS**
 - Shows flow of data through each component.
 - HW -> SW -> HW.
- **COMP.1.1.5.6 Police Report Software**
 - Shows flow of data through each function.



Physical Interfaces

- Interfaces connect COMP-COMP or COMP-EXT.
- Interfaces are designed like components.
- Performs a function and traces back to a REQ.

Number	Name	Implementation	What is Passed	Source	Destination	Connects To	Function / Functional Interaction
INT.0.7.1	GPS Satellite / Personnel GPS	GPS Signal	Timing Data	GPS	Personnel GPS	COMP.1.1.4.8 Personnel GPS COMP.14 GPS Satellite	FUNC.4.5 / GPS
INT.0.9.3	Driver / Steering Wheel	Driver Hands	Turning Force	Driver	Steering Wheel	COMP.1.1.1.4.1 Steering Wheel COMP.2.3 Driver	FUNC.2.5 / Driver
INT.0.10.4	Incident Vehicles / Interactive Panorama Assembly	DSLR Camera	Photograph Data	Incident Vehicles	Interactive Panorama Assembly	COMP.1.1.5.5 Interactive Panorama Assembly COMP.7 Incident Vehicles	FUNC.5.4 / Incident Vehicles
INT.1.1.1.11	Engine / Gas Tank	Fuel Line	Gasoline Material	Gas Tank	Engine	COMP.1.1.1.3.2 Gas Tank COMP.1.1.1.3.3 Engine	FUNC.9.2 / FUNC.9.3
INT.1.1.1.30	Navigation Assembly / Vehicle Power Assembly	Wire (14 gauge)	Electricity Energy	Vehicle Power Assembly	Navigation Assembly	COMP.1.1.1.2 Navigation Assembly COMP.1.1.1.3 Vehicle Power Assembly	FUNC.9.4 Transfer Power to Components

Trade Study – Criterion and Alternatives

- Criterion

- Height
- Setup Time
- # Setup Personnel
- Ability to Handle Wind
- Volumetric Storage

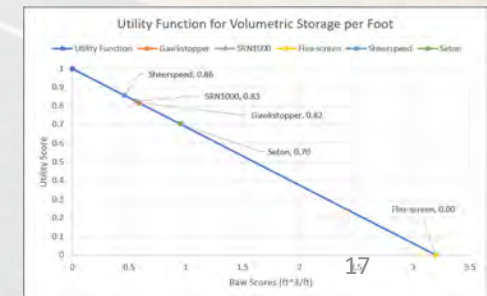
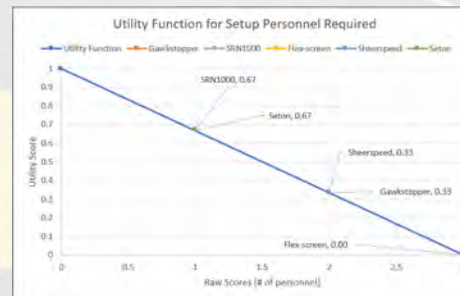
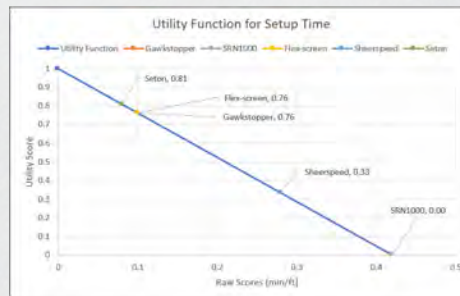
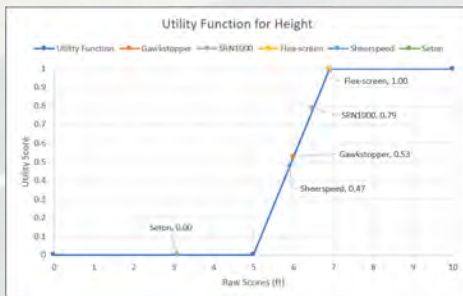
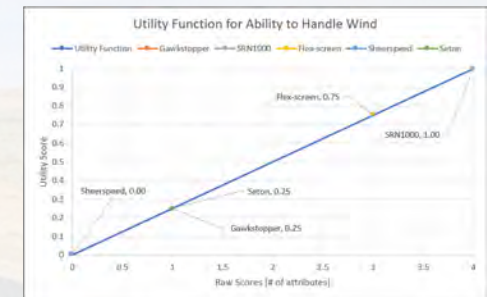


Trade Study – Weights and Utility Functions

- Weighting
 - Pairwise comparison and Squared Matrix
- Utility Functions
 - All Linear
 - POS. or NEG. slope based on “max-ing” or “min-ing” the criterion.

	Height	Setup Time per Foot	Setup Personnel Required	Ability to Handle Wind	Volumetric Storage per Foot
Height	1.00	5.00	0.33	0.14	1.00
Setup Time per Foot	0.20	1.00	1.00	0.33	4.00
Setup Personnel Required	3.00	1.00	1.00	3.00	5.00
Ability to Handle Wind	7.00	3.00	0.33	1.00	5.00
Volumetric Storage per Foot	1.00	0.25	0.20	0.20	1.00

	Height	Setup Time per Foot	Setup Personnel Required	Ability to Handle Wind	Volumetric Storage per Foot	Sum	Normalized Results
Height	5.00	11.01	5.91	3.15	24.38	49.46	0.16
Setup Time per Foot	9.73	5.00	2.98	4.50	14.87	37.07	0.12
Setup Personnel Required	32.20	27.25	5.00	7.76	32.00	104.21	0.33
Ability to Handle Wind	20.60	42.58	7.00	5.00	30.67	105.85	0.34
Volumetric Storage per Foot	4.05	6.30	1.05	1.23	5.00	17.63	0.06
					TOTAL:	314.22	1.00



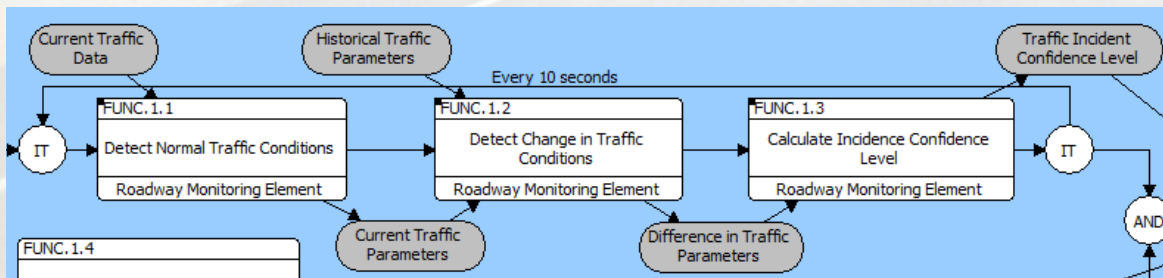
Trade Study – Final Decision

Criteria	Criteria Weights	Gawkstopper		SRN1000		Flex-screens		Sheerspeed		Seton	
		Unweighted Scores	Weighted Scores	Unweighted Scores	Weighted Scores	Unweighted Scores	Weighted Scores	Unweighted Scores	Weighted Scores	Unweighted Scores	Weighted Scores
Height	0.16	0.53	0.08	0.79	0.12	1.00	0.16	0.47	0.07	0.00	0.00
Setup Time per Foot	0.12	0.76	0.09	0.00	0.00	0.76	0.09	0.33	0.04	0.81	0.07
Setup Personnel Required	0.33	0.33	0.11	0.67	0.22	0.00	0.00	0.33	0.11	0.67	0.07
Ability to Handle Wind	0.34	0.25	0.08	1.00	0.34	0.75	0.25	0.00	0.00	0.25	0.02
Volumetric Storage per Foot	0.06	0.82	0.05	0.83	0.05	0.00	0.00	0.86	0.05	0.70	0.03
Operational Utility Function (Weighted Sum)		41.28		73.00		49.97		27.06		19.92	
Cost (\$)		240		192		114		30		18	
Cost-Effectiveness Selection Function (Weighted Sum / Cost)		0.17		0.38		0.44		0.90		1.11	

- Final Selection Reasoning:
 - Are all requirements met?
 - Balance of Operational Utility and Cost Effectiveness?
 - Additional benefits?

Test Plan

- COMP.1.2 Roadway Monitoring Element
- Objectives
 - Verification of performance requirements specified by and functional requirements performed by this subsystem.
 - Reduction of risk (ID:06) in the network performance of the roadway monitoring element.
 - Demonstrate successful integration of subsystem components.



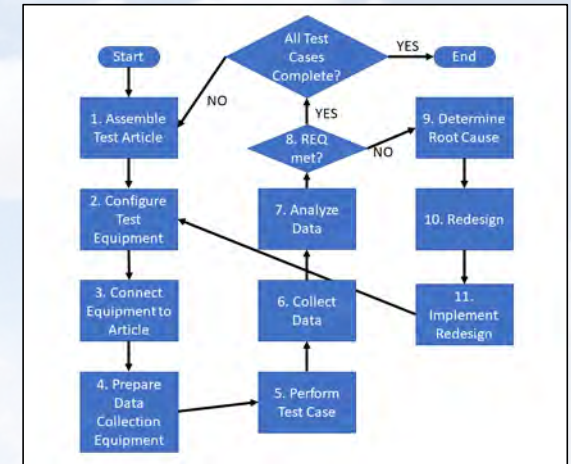
Number	Name	Requirement
REQ.2.2	Detect	The system shall detect when a traffic incident has occurred within 20 seconds (O) 30 seconds (T) of the occurrence.
REQ.2.2.2	Compare Conditions	The roadway monitoring subsystem shall compare current traffic conditions to historic traffic conditions.
REQ.2.2.2.1	Historic Traffic Conditions	The roadway monitoring subsystem shall maintain a database of 500 (O) 100 (T) historical traffic conditions on the roadways that are monitored.
REQ.2.2.2.2	Confidence Level	The roadway monitoring subsystem shall calculate a confidence level that a traffic incident has occurred every 5 seconds (O), 10 seconds (T).
REQ.2.2.2.3	Incident Confidence Calculation	The roadway monitoring system shall use change in traffic speed, density, and visual changes to determine a final level of confidence that a traffic incident occurred.
REQ.2.2.2.4	Traffic Speed Magnitude	The roadway monitoring subsystem shall measure the speed of traffic passing to within 1 mph (O), 5 mph (T).
REQ.2.2.2.5	Traffic Speed Update Frequency	The roadway monitoring subsystem shall measure the speed of passing traffic at least every 5 seconds (O), 10 seconds (T).
REQ.2.2.2.6	Traffic Density Magnitude	The roadway monitoring subsystem shall measure the distance between each passing vehicle to a maximum of 5 ft (O), 25 ft (T).
REQ.2.2.2.7	Traffic Density Update Frequency	The roadway monitoring subsystem shall measure the traffic density at least every 5 seconds (O), 10 seconds (T).
REQ.2.2.2.8	Traffic Visual	The roadway monitoring subsystem shall capture images of the traffic conditions with a resolution of at least 1080p.
REQ.2.2.2.9	Traffic Visual Update Frequency	The roadway monitoring subsystem shall record an image of traffic at least one every 5 seconds (O), 15 seconds (T).
REQ.2.2.2.10	Night Time	The roadway monitoring subsystem shall have electrical storage to operate for 72 hours (O), 60 Hours (T) without sunlight.
REQ.2.2.2.11	Power Generation	The roadway monitoring subsystem shall generate its daily power usage in a maximum 4 hour (O), 5 hour (T) period of sunlight.
REQ.2.2.3	Element Interface	The interface between the Roadway Monitoring Element and the Response Vehicle Element shall transfer data with a latency of no more than 100 ms (O) 500 ms (T).
REQ.2.2.3.1	Network of Nodes	The roadway monitoring element and response vehicle interface shall support up to 5000 (O) 1000 (T) network nodes.

Test Plan

- Environment: SIL with closed driving course.
- Equipment: Traffic simulators and real traffic.
- Units Under Test: 10 builds over 34 Test Cases.
- Integration, Qualification, and Field Test Cases.

- Process:

- Build Article
- Setup Equipment
- Perform Test
- Collect and Analyze Data
- Determine if REQ was met



#	Metric	Units	Requirement	Objective Value	Threshold Value
1	Structural	True/False	-	True	True
2	Interoperability	True/False	-	True	True
3	Detection Time	Seconds	REQ.2.2	20 sec	30 sec
4	Comparison to Historic Functionality	True/False	REQ.2.2.2	True	True
5	Entries in Database	Count	REQ.2.2.2.1	500	100
6	CI Update Speed	Seconds	REQ.2.2.2.2	5 sec	10 sec
7	CI Calculation Functionality	True/False	REQ.2.2.2.3	True	True
8	Speed Sensor Accuracy	MPH	REQ.2.2.2.4	1 MPH	5 MPH
9	Speed Sensory Update Frequency	Seconds	REQ.2.2.2.5	5 sec	10 sec
10	Density Sensor Accuracy	Feet	REQ.2.2.2.6	5 feet	25 feet
11	Density Sensor Update Frequency	Seconds	REQ.2.2.2.7	5 sec	10 sec
12	Image Resolution	Pixels	REQ.2.2.2.8	1080p	1080p
13	Image Capture Frequency	Seconds	REQ.2.2.2.9	5 sec	15 sec
14	Electricity Usage Efficiency	Hours	REQ.2.2.2.10	72 hours	60 hours
15	Power Generation Efficiency	Hours	REQ.2.2.2.11	4 hours	5 hours
16	Data Transfer Latency	Millisecond	REQ.2.2.3	100 ms	500 ms
17	Network Nodes	Count	REQ.2.2.3.1	5000	1000

System Specification – Requirements Summary

- Focus changed throughout semester:
 - Capture all REQs.
 - Add REQs based on the current deliverable.
 - Add REQs based on new info.
 - Revise/modify REQs to improve maturity and be quantitative.

Report	Total	Quantitative	Binary	Qualitative
Requirements Analysis Report	105	27 (25.7%)	57 (54.3%)	21 (20.0%)
Functional Analysis Report	123	36 (29.3%)	65 (52.8%)	22 (17.9%)
Trade Study	128	39 (30.5%)	67 (52.3%)	22 (17.2%)
Conceptual Design Report	130	39 (30%)	69 (53.1%)	22 (16.9%)
System Specifications	133	89 (66.9%)	37 (27.8%)	7* (5.2%)
% Change from RAR	+ 26.6%	+229.6%	-35.1%	-66.6%

*Includes 7 User Need requirements.

System Specification - KPPs

- Set of requirements that must be met for customer to accept the system.
- Based on core/primary user needs.

Number	Name	Description	Type	Rationale
REQ.1.2.2	Speed (KPP)	The system shall achieve a forward speed of at least 80 mph (O), 70 mph (T).	Quantitative	https://en.wikipedia.org/wiki/Speed_limits_in_the_United_States Facilitates rapid incident response time and does not skew the performance based on the distance between the stand-by location and the incident. [1]
REQ.2.4.4	Interactive Panorama (KPP)	The incident documentation subsystem shall create an interactive panorama of the entire incident scene within 5 minutes (O)(T) of arrival.	Quantitative	https://www.youtube.com/watch?v=BQ8HZd3psr0 Timestamp 23:45 [2]
REQ.3.1.2	Trained Personnel (KPP)	The medical response subsystem shall facilitate trained personnel to attend to the injured within 15 seconds (O), 30 seconds (T) of arrival on scene.	Quantitative	Directly decreases the Incident Clearance Time, an important MOE for the system, through increased efficiency of a sub-step of the entire process.
REQ.4.1	Commander (KPP)	The system shall be commanded by maximum one person.	Quantitative	TIMS Handbook paragraph 3.2.2 One incident commander is important to control the resolution activities and to be the final decision maker. [3]
REQ.5.1	Removal (KPP)	The removal subsystem shall remove vehicles and debris from the travel lanes within 10 minutes (O), 20 minutes (T). Time starts once all medical needs have been attended to, and the scene is properly documented.	Quantitative	Directly decreases the Incident Clearance Time, an important MOE for the system, through increased efficiency of a sub-step of the entire process.
REQ.6.3	Prevent Rubbernecking (KPP)	The manage passing traffic subsystem shall minimize the line of sight between passing drivers and the incident scene to achieve less than one secondary incident out of every 30 primary incidents. (Compared to this study which found a secondary incident occurred once every 24.8 primary incidents. http://people.virginia.edu/~njg2q/secondary.pdf) [4]	Quantitative	https://rosap.nhtl.bts.gov/view/dot/29634 "As far as the factor of barrier is concerned, the coefficient is negative. It implies that the presence of barriers on an accident scene decreased the likelihood of rubbernecking in the opposite direction. This may be due to blocking of the barriers for the motorists to view the accidents in the other direction." "Barriers are an effective way to reduce the likelihood of rubbernecking in the opposite direction and the delay caused by the rubbernecking. This conclusion is drawn upon the coefficients of the variable barrier in the models for the likelihood of rubbernecking occurrence and traffic delay." [5]

Risk Management - Summary

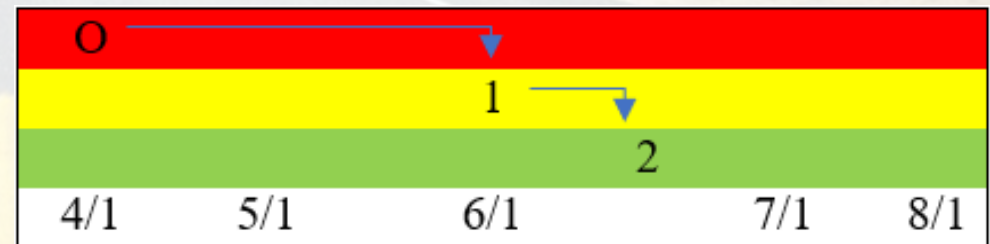
ID	Title	Risk	Type	Original Score	Current Score
1	Deliverable Schedule	If the systems engineering process takes longer to complete than scheduled then the project will not finish during Summer 2020 semester.	Schedule	3, 5 Red	0, 0 Green
2	Incident Sensing and Documentation	If the incident sensing subsystem cannot quickly and accurately document the incident scene then the roadway clearance time will significantly increase in order to complete the incident investigation.	Technical	3, 5 Red	2, 5 Yellow
3	Emergency Medical Response	If the emergency medical response is not as good as current EMS standards then the clearance of the roadway will be delayed by the medical response function.	Technical	3, 4 Yellow	1, 4 Green
4	Traffic Management	If the manage traffic subsystem cannot reduce the amount of rubbernecking then the number of secondary incidents won't decrease.	Technical	4, 4 Red	1, 4 Green
5	Implemented System Density	If the density of implemented TIMS is not large enough then response time will be increased.	Cost / Operational	4, 5 Red	4, 5 Red
6	Network of Roadway Monitoring Elements	If the bandwidth of the network is not sufficient to handle all of the data then the system will not identify when an incident occurred and it will not respond quickly.	Technical	3, 5 Red	2, 5 Yellow
7	Incident Action Plan Recommendations	If the incident action plan recommendation software does not utilize past incident data then the response efficiency will not improve.	Technical	4, 5 Red	3, 5 Red

Risk Management – Risk ID 04

- **Risk ID 04: Traffic Management**
- If the “manage traffic” subsystem cannot reduce the amount of rubbernecking then the number of secondary incidents won’t decrease.
- *Type:* Technical
- *Original Score (O):* 4, 4
- L: 4 (No technology in US is widely used for this function)
- C: 4 (Significant degradation in performance)

#	Mitigation Steps	ECD	ACD	L	C
1	Decompose functions that will facilitate achieving the MOE.	5/31/20	6/5/20	3	4
2	Complete the trade study on this subsystem to physically allocate a proven COTS item.	6/12/20	6/12/20	1	4

Likelihood	5	Green	Yellow	Red	Red	Red
	4	Green	Yellow	Yellow	Red (O)	Red
	3	Green	Green	Yellow	Yellow (1)	Red
	2	Green	Green	Green	Yellow	Yellow
	1	Green	Green	Green	Green	Yellow (2)
			1	2	3	4
		Consequence				



Summary and Next Steps

- System Engineering Process was used to develop this preliminary Traffic Incident Management System Architecture.
- Hold some SETRs
 - System Requirements Review, System Functional Review, Integrated Baseline Review
- Further iteration of the SE process needs to occur.
 - Derive requirements further
 - Decompose functions further
 - Allocate lower physical components
 - Perform more trade studies
 - Identify more interfaces

Lessons Learned

- CORE is a great tool, but has some limitations
 - University Edition
 - Physical N2 diagram labels
- Stakeholders are very important
 - Can be consulted in all areas of the process.
- Questions to ask during requirements development
 - What criterion would I use in a Trade Study?
 - What objectives need to be tested?

Recommendations

- Proposals being due before registration is good.
 - Find additional ways to engage students very early.
- 800 Capstone course should increase focus on cost.
 - Operations and Support costs are decided in the design.
 - No focus to decrease or determine them.
- Add “Logistics type” section in current deliverable.
 - FMECA to decrease risk?

A long, straight asphalt road stretches from the foreground into the distance, flanked by a sandy, arid landscape. The road has a dashed yellow center line and solid white edge lines. The sky is filled with large, white, fluffy clouds against a pale blue background. The overall scene is bright and open.

Thanks Steve!